Investigating Explosion Source Energy Partitioning and *Lg*-Wave Excitation Using a Finite-Difference plus Slowness Analysis Method

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Abstract A finite-difference modeling plus slowness analysis method is developed to investigate near-source explosion energy partitioning and Lg-wave excitation. The finite-difference method is used to calculate seismic wave excitation and propagation, and an embedded array slowness analysis is used for quantifying how energy will be partitioned into the long-range propagation regime. Because of its high efficiency, the method can simulate near-source processes using very fine structures. A large number of source and model parameters can be examined for broad-frequency ranges. As examples, P-pS-to-Lg and S*-to-Lg conversions in the presence of near-source scattering are tested as mechanisms for Lg-wave excitation. The numerical results reveal that the depth of the source and the depth of the scattering process have strong effects on P-to-S conversion and partitioning of energy into trapped or leaking signals. The Lg-wave excitation spectra from these mechanisms are also investigated. The modeling shows that S*-to-Lg excitation is generally stronger for low frequencies and shallow source depths whereas P-pS-to-Lg scattering is stronger for high frequencies.

Introduction

With the current emphasis on global monitoring for low-yield nuclear tests, regional seismic phases such as Lg have become very important for magnitude and yield estimation of underground nuclear tests (Nuttli, 1986; Xie, et al., 1996; Patton, 2001). In addition, various P/S-type amplitude ratios for high-frequency regional phases (e.g., Pn/ Sn, Pn/Lg, Pg/Lg, Pg/Sn) have become important for event discrimination (Taylor et al., 1989; Kim et al., 1993, 1997; Walter et al., 1995; Fisk et al., 1996; Taylor, 1996; Taylor and Hartse, 1997; Hartse et al., 1997; Fan and Lay, 1998a-1998c; Xie, 2002; Bottone et al., 2002). The applications of regional phases for yield estimation and event discrimination are largely based on empirical approaches, and, although very promising in many cases, major questions exist about the nature of excitation of S-wave-dominated phases such as Lg. There are similar questions regarding the relative excitation effects for P/S-type ratios in regional phases, in particular, given the huge scatter observed in both earthquake and explosion data populations.

There are now many observational and theoretical studies addressing the regional phase energy-partitioning issue in both the near-source environment and the propagation-path environment. Along the propagation path, the existence of small-scale heterogeneities in the crust and the associated seismic wave scattering has long been addressed by seismologists (Wu and Aki, 1988; Sato and Fehler, 1998), and its effect on the long-range energy partitioning has been doc-

umented (Wu *et al.*, 2000a, 2000b). In the source region, several possible near-source energy excitation mechanisms have been proposed, including *P*-to-*Lg* scattering, *pS*-to-*Lg* conversion at the free surface, *Rg*-to-*Lg* coupling, *S**-to-*Lg* conversion, spall excitation of *S*, tectonic release, and rock damage (Gutowski *et al.*, 1984; Lilwall, 1988; Day and Mclaughlin, 1991; Gupta *et al.*, 1992, 1997; Wallace, 1991; Xie and Lay, 1994; Vogfjord, 1997; Johnson and Sammis, 2001).

Because of the complex excitation and energy-partitioning processes associated with regional phases, it is difficult to empirically separate the contribution of individual energypartitioning mechanisms by analysis of data. Numerical modeling approaches are thus of great importance for investigating the excitation and propagation of regional phases. Kennett and Mykkeltveit (1984) and Kennett (1989) used the coupled-mode method to calculate Lg-wave propagation in crustal wave guides with weak lateral heterogeneities. Xie and Lay (1994) investigated Lg-wave excitation using the full-wave finite-difference (FD) method. Jih (1995, 1996) investigated Rg-to-Lg coupling as a possible Lgexcitation mechanism. With an anelastic FD method, Bradley and Jones (1998, 1999) investigated Lg propagation and attenuation in Western China and India. Recently, using the 2D and 3D general Fourier methods, Bonner et al. (2003) investigated Rg and Lg generation and partially reproduced the observed spectrum from the Depth of Burial Experiment.

Stevens *et al.* (2003) investigated the physical basis of explosion-generated *S*-waves using a 2D nonlinear FD method, which handles axisymmetric near-source effects, including spall, cracking, and nonlinear deformation.

The main disadvantages of these numerical methods are their low computation efficiency and huge computer memory requirement, especially when applied to investigate broadband Lg excitation. For the purpose of small nuclear test monitoring, the range of interest for Lg-wave simulation involves a broad-frequency band (0.2-10 Hz) and long propagation distances (up to 1000 km or more). At the same time, factors that control the source energy partitioning depend on the detailed source mechanism and fine near-source velocity structure. In addition, multiple mechanisms may potentially contribute to the energy-partitioning process. Numerous parameters need to be tested to investigate the characteristics of these mechanisms, especially their contributions to the frequency-dependent features of observable discriminants. If random heterogeneities are to be considered, as is likely to be important for high-frequency signals, the results have to be calculated statistically from simulations using a large number of realizations. These factors limit the approach of complete FD synthesis for actual recording geometries.

Although there are continuing controversies about the dominant P-to-S transfer mechanisms affecting regional phases, most investigators agree that appreciable energy from explosion sources is converted to S waves in the nearsource region (Myers et al., 2003). The physical processes by which an explosion source generates regional phases can be described as energy partitioning taking place in the nearsource region. The partitioned energy subsequently propagates through a long wave guide, where secondary energypartitioning effects may occur, but these are less affected by the type of source involved. If the propagation effect is not of primary interest, it is desirable to avoid calculating the immensely time-consuming long-distance propagation part of the problem. To focus on the near-source energypartitioning processes, we developed a method based on the FD simulation and local slowness analysis. This method investigates energy partitioning right at the source region but quantifies how energy will transfer into the long-range propagation path, which is critical for comparisons with data. The localized analysis thereby isolates the physical processes controlling the energy partitioning.

In the following sections, we first present the method with numerical calculations used to demonstrate its validity. Then, by investigating two potential Lg-wave excitation mechanisms, we demonstrate how this method can be used to investigate explosion source energy partitioning. This article does not provide a complete investigation of all Lg-wave excitation mechanisms. Many important issues, e.g., the effects of free surface topography and dipping structures, Rg-to-Lg conversion, and contributions from secondary sources, will be addressed in future work.

Methodology

We limit our 2D FD simulation to a relatively small model and analyze the wave field within the model to investigate the source energy partitioning and the excitation of trapped regional phases such as Lg. Many authors (e.g., Frankel, 1989; Xie and Lay, 1994; Vogfjord, 1997) have pointed out that for S-wave energy to be trapped in the wave guide, reverberating to generate the Lg-wave, it must propagate with postcritical angle at the Moho discontinuity. However, in the wave guide and especially in the nearsource region, the wave field is highly complex. It is impractical to trace each phase in the spatial-time domain. An alternate but equally valid way of tracking the wave energy is in the slowness domain. Multiply reflected waves may arrive simultaneously in time, but in the slowness domain their energy distribution gives clear information about the wave intensity, slowness, and propagation direction. Several methods can be used to transfer spatial-time domain data into slowness (or equivalently wavenumber) domain information, for example, frequency-wavenumber analysis or slant stacking. Here we use a local slant-stacking method to conduct slowness analysis, working simultaneously in both the space and slowness domains. We call this the finite-difference slowness analysis (FDSA) method.

Local Slowness Analysis

Two-dimensional local slant stacking in the horizontal and vertical directions can be expressed as:

$$\mathbf{u}(\mathbf{r}, \mathbf{p}, t, \omega) = \frac{1}{C_1} \sum_{r'} W_R(\mathbf{r}' - \mathbf{r})$$
$$\mathbf{u}[\mathbf{r}', t - \mathbf{p} \cdot (\mathbf{r}' - \mathbf{r}), \omega], \quad (1)$$

where $\mathbf{r} = x\mathbf{\hat{e}}_x + z\mathbf{\hat{e}}_z$ is the 2D position vector, $\mathbf{\hat{e}}_x$ and $\mathbf{\hat{e}}_z$ are unit vectors in the x and z direction, \mathbf{r}' is the location of the receiver, t is time, $\mathbf{u}(\mathbf{r}, t, \omega)$ is the bandpass-filtered synthetic seismogram with central frequency ω , $W_R(\mathbf{r}' - \mathbf{r})$ is a twodimensional space window centered at \mathbf{r} , $\mathbf{p} = p\hat{\mathbf{e}}_p$ is the slowness vector, $\hat{\mathbf{e}}_p$ is the unit vector of the slowness direction, $p = v^{-1}$ is the wave slowness, $v = v_p$ or $v = v_s$ is Por S-wave velocity, C_1 is a normalization factor determined by the size of the space window and bandwidth of the frequency filter. The space window is for a small vertical seismic array with size related to both space resolution and slowness resolution. A larger array gives better slowness resolution but tends to smear the spatial resolution, whereas a small array gives better spatial resolution but less accurate slowness calculation. A proper trade-off between space and slowness resolution is required. The receiver interval should be small enough to avoid spatial aliasing. The average energy density of the wave field as a function of space, time, slowness, and frequency can be obtained as

$$D(\mathbf{r}, \mathbf{p}, t, \omega) = \rho \overline{\dot{u}^2}(\mathbf{r}, \mathbf{p}, t, \omega), \tag{2}$$

and the energy flux related to slowness vector \mathbf{p} can be calculated as

$$\mathbf{J} = vD(\mathbf{r}, \mathbf{p}, t, \omega)\hat{\mathbf{e}}_{p}, \tag{3}$$

where ρ is the density and $\overline{u}(\mathbf{r}, \mathbf{p}, t, \omega)$ is the root-mean-square (rms) amplitude of the stacked velocity seismogram $\dot{\mathbf{u}}(\mathbf{r}, \mathbf{p}, t, \omega)$. Similarly, the 1D horizontal slant stack can be calculated as

$$\mathbf{u}(\mathbf{r}, p_x, t, \omega) = \frac{1}{C_2} \sum_{x'} W_R(x' - x, z)$$

$$\mathbf{u}[x', z, t - p_x(x' - x), \omega], \quad (4)$$

where $p_x = p\mathbf{\hat{e}}_p \cdot \mathbf{\hat{e}}_x$ is the horizontal slowness, $W_R(x' - x, z)$ is a 1D space window, and C_2 is a normalization factor similar to C_1 in equation (1). The average energy density as a function of p_x can be expressed as

$$D(\mathbf{r}, p_x, t, \omega) = \rho \overline{\dot{u}^2}(\mathbf{r}, p_x, t, \omega). \tag{5}$$

The pure horizontal energy flux related to horizontal slowness p_x can be obtained from equation (3)

$$J_h(\mathbf{r}, p_x, t, \omega) = \int \mathbf{J}(\mathbf{r}, \mathbf{p}, t, \omega) \cdot \hat{\mathbf{e}}_x dp_z.$$
 (6)

Alternatively, J_h can be calculated from horizontal slant stacking, i.e., equations (4) and (5).

$$J_h(\mathbf{r}, p_x, t, \omega) = vD(\mathbf{r}, p_x, t, \omega) \cdot \hat{\mathbf{e}}_P \cdot \hat{\mathbf{e}}_x$$
 (7)

where $\hat{\mathbf{e}}_p \cdot \hat{\mathbf{e}}_x = vp_x = \sin i$ and i is the wave-incident angle (relative to the vertical direction). In the wave guide, the energy passing through a surface S within a frequency range Ω , a time window T, and a slowness band P can be calculated as:

$$E(S, P, T, \Omega) = \int_{S} \int_{P} \int_{T} \int_{\Omega} \mathbf{J} \cdot \hat{\mathbf{e}}_{n} \, d\omega \, dt \, d\mathbf{p} \, ds, \quad (8)$$

where $\hat{\mathbf{e}}_n$ is the unit normal vector of the surface element ds, and $d\mathbf{p} = dp_x dp_z$. When choosing a vertical intersection as the surface, equation (8) becomes

$$E(S, P, T, \Omega) = \int_{S} \int_{P} \int_{T} \int_{\Omega} J_{h} d\omega dt dp_{x} dz.$$
 (9)

Equations (8) and (9) provide the basis for extracting energy from joint domains. To investigate the near-source energy partitioning and regional phase excitation, the energy generated from specific mechanisms is decomposed into multiple domains and analyzed based on its dynamic and kinematic properties. The condition for energy to be trapped in the crustal wave guide, i.e., $p_x \ge 1/v_{S-\text{mantle}}$ (where $v_{S-\text{mantle}}$ is the upper-mantle S velocity) is applied. We then use the joint window (S, P, T, Ω) to sort the trapped energy and estimate the contribution of specific mechanisms to regional phases such as Lg. Equations (8) or (9) can be partially integrated, which allows the energy to be projected onto different domains. The analysis within multiple domains provides additional information to characterize the contributions from different mechanisms. This method has the flexibility that we can either intercept the entire wave-guide energy flux or just monitor the energy from specific phases or mechanisms. The calculation using 2D slowness analysis has the advantage that energy is fully expanded in the entire slowness domain. The slowness vector **p** for both *P*- and *S*waves can be obtained independently, giving us more information to investigate complicated near-source processes. The calculation based on 1D slowness analysis gives the energy as a function of horizontal slowness p_x . It provides the necessary information to separate the trapped and leaking energy. Although it does not directly give the full slowness domain information, by combining dynamic and kinematic characteristics, we can resolve the near-source phenomena in most cases without ambiguity.

Equations (8) and (9) are expressed with energy, because energy can be directly summed. However, regional phase observations are usually taken from amplitudes. To compare the numerical prediction with observations, we calculate the normalized square root of the energy

$$A = (E/E_0)^{1/2}, (10)$$

where E_0 is a normalization factor that can be obtained by calculating the response of a unit source. The unit source is located at unit distance in an infinitely homogeneous model. It has a unit intensity, the same source time function as that used in the simulation and its response passes through the same frequency filter. Normalized square root energy A is consistent with the conventional Lg-wave measurement based on the rms amplitude of the waveforms. Another advantage of using A is that the variation of amplitude distribution is smoother than the variation of energy. For these reasons, throughout this article, we will use the normalized square root energy in all figures although we sometimes simply call it "energy."

Figure 1 shows examples of 1D and 2D slowness analyses. The energy can either be expressed as a function in 2D slowness domain, or as a function in the mixed slowness—depth domain. For references, the upper-mantle S slowness $P_{SM} = 1/v_{S-mantle}$, crustal P slowness $P_{SM} = 1/v_{S-mantle}$, crustal P slowness $P_{SM} = 1/v_{S-mantle}$ are labeled in the figure, with $v_{S-mantle} = 4.57$ km/sec, $v_{P} = 6.0$ km/sec, and $v_{S} = 3.5$ km/sec. All S-wave energy with horizontal slowness larger than the uppermantle S slowness, whether directly radiated from the source or generated as secondary phases, will be trapped in the crustal wave guide and will contribute to the guided regional

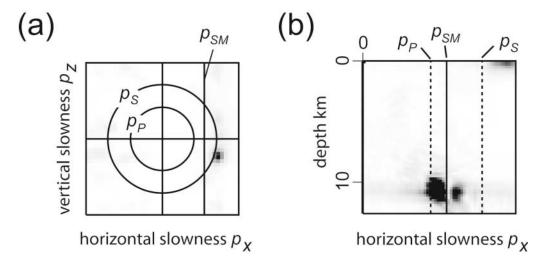


Figure 1. Slowness domain display with (a) energy distribution in 2D slowness domain and (b) energy distribution in mixed horizontal slowness and depth domain. Vertical lines indicate the upper-mantle S slowness p_{SM} . Circles and dashed lines denote crustal P-wave slowness, p_P , and S-wave slowness, p_S . Energy falling to the right of upper-mantle S slowness can be trapped in the wave guide and contribute to L_S .

phases unless subsequent scattering causes it to leak out. Figure 2 is a sketch showing the configuration of the FDSA method for investigating the near-source processes. The model uses an explosion source, a fine-scale near-source velocity model, and a short-distance receiver array to provide synthetic seismograms for the ensuing slowness analysis.

Figure 3 gives an example of slowness analysis. Shown on the top is the synthetic seismogram at the center of the mini array. In the middle are energy distributions for P coda, Lg and Rg waves in 2D slowness domain. These energy distributions clearly show that the P coda is composed of P and reflected pS waves. Both of these have relatively small horizontal slowness. The Lg wave is composed of multiply reflected S waves. Its energy falls on the S-wave slowness circle, and part of the energy stays on the right of the uppermantle S slowness and forms trapped phases. The Rg wave is also a trapped mode with horizontal slowness larger than the S slowness. Shown at the bottom of Figure 3 is the energy isolated by the slowness analysis. The horizontal axis is time or, equivalently, the inverse of the group velocity. The vertical coordinate is the horizontal slowness or, equivalently, the apparent horizontal-phase velocity. The filled circles are energy measured in the slowness domain with their sizes being proportional to the amount of energy. The horizontal dashed line marks the upper mantle S slowness that divides the trapped and leaky energy.

Testing the Validity of the Method

We will first check the validity of the FDSA method by comparing the energy partitioning predicted at short distances using slowness analysis with the energy measured from long-distance surface receivers via a conventional method. For all numerical examples calculated in this article,

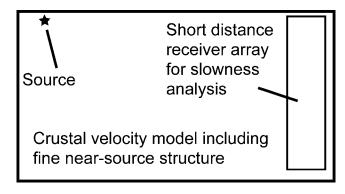


Figure 2. Configuration for using the FDSA method to investigate near-source processes.

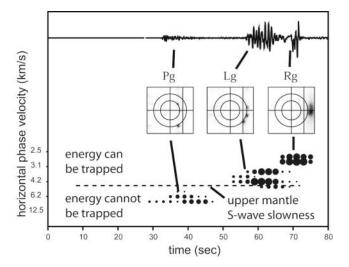


Figure 3. Example of slowness analysis at 180 km distance.

unless otherwise indicated, we use the horizontally layered Eastern Kazakh (EK) model (Priestley et al., 1988) as the background and modify it by adding random velocity fluctuations at different locations. The EK model (Table 1) has a high-velocity top layer with $v_P = 5.05$ km/sec and an upper-mantle S-wave velocity $v_{S-\text{mantle}} = 4.57 \text{ km/sec.}$ For this layered model, P waves radiated from an explosive source cannot be effectively converted to trapped S waves. The random velocity perturbations added have an exponential power spectrum with horizontal and vertical correlation lengths equal to 0.5 km. We call the part of the model with velocity perturbations the "random patch." Within the patch, both P- and S-wave velocities have the same relative rms perturbation, and the relative density perturbation is 50% of the relative velocity perturbation. To eliminate the possible effect of sharp edges of these random patches, a space window with smoothed edges is applied to the patch. The sizes, locations, and the rms perturbations of these patches will vary depending on the purpose of the investigation.

We first test models with scattering at different depths by varying the location of random patches within the EK model. These patches are 2.5 km in vertical extent, extend horizontally from 5 to 25 km, and are located at different depths. Within the patches, the P- and S-wave velocities have 10% rms fluctuations. An explosion source is located at depth 0.5 km. Figure 4 shows the slowness analysis results at a distance of 180 km in the crustal wave guide. Panels a and b are for frequencies 0.3-1.5 Hz and 2.0-5.0 Hz, respectively. Each panel is similar to the example shown in Figure 3. The top row is for the background velocity model and the other rows are calculated for models with nearsource random velocity perturbations. The depths of the random patches are labeled in the figure. We first focus on the low-frequency results in Figure 4a. For the background velocity model, there is a strong Rg phase but very little energy within the Lg group velocity window of 3.0–3.5 km/sec, which is typical for a crustal model with a high-velocity top layer. For models with random velocity patches, compared with the background model, considerable energy is transferred to the Lg-wave through scattering, while the Rg wave is weakened. The shallower the random patch, the more en-

Table 1
Eastern Kazakh Model

Top of Layer (km)	V_P (km/sec)	V_S (km/sec)	ρ (g/cm ³)
0.0	5.05	2.91	2.70
1.0	5.66	3.21	2.70
5.0	5.55	3.17	2.70
10.0	6.01	3.41	2.70
15.0	6.29	3.55	2.90
25.0	6.65	3.73	2.90
30.0	6.89	3.85	2.90
45.0	7.59	4.20	3.00
47.5	8.33	4.57	3.30

ergy is scattered into Lg. For the EK model, which has a thick, high-speed crust, the distance for Pn to cross Pg at the free surface is about 200 km. At 180 km distance, there is no prominent Pn energy shown in this analysis.

For high-frequency results in Figure 4b, from the top panel we see strong Pg energy. There is also energy within the Lg-group velocity window. However, this energy has a similar horizontal slowness to the Pg wave, implying that it is generated from Pg through P-to-P and P-to-S reflections on the free surface and interfaces such as the Moho discontinuity. Although the energy exists at short distances, the steep incident angle causes energy to gradually leak to the upper mantle through multiple reflections and it cannot form trapped regional phases. In the other panels, after adding random velocity perturbations in the near-source region, part of the P energy transfers to the Lg wave, i.e., energy falls into the proper group velocity and slowness windows. In general, the scattering affects Rg-to-Lg energy at low frequencies and P-to-Lg coupling at high frequencies. Summing up energy through the wave-guide cross section and within the proper time (group velocity) windows allows the energy for the related wave types to be obtained. Specifically, summing up the energy located within the Lg-group velocity window and above the upper-mantle S slowness allows Lg energy at long distances to be predicted. It is necessary to confirm this calculation.

Figure 5 compares the wave-guide energy obtained using different methods. The left panel shows the square root energy passing through the wave-guide cross section at 180 km calculated from the slowness analysis shown in Figure 4. The right panel shows the rms amplitudes at 450 km calculated by using a conventional processing technique (i.e., computing surface synthetic seismograms, applying frequency filters and group velocity windows to isolate different phases, and calculating rms amplitudes for these phases). The same velocity model used in Figure 4 is adopted here and a full-scale FD simulation is computed to provide data up to 500 km distance. For simplicity, we label the predicted trapped energy as "Lg" energy. The relative energy changes of Pg, Lg, and Rg waves, as functions of the depth of the random velocity patches are shown in Figure 5. The calculations for different phases demonstrate that the relative change of energy obtained in the wave-guide slowness analysis corresponds closely to that obtained on the free surface, even for dramatic changes such as the strong scattering of Rg. The results confirm that the slowness analysis within the wave guide correctly predicts the surface regional observations at greater distances.

To examine the energy-flux measurements obtained at even shorter distances, we compare the slowness analysis measurements at 50 km with those at 100 km. For these two distances, Figure 6 gives examples of horizontal slowness analyses, which show quite different features in the slowness–depth domain because of evolution of the wave field with range. Figure 7 compares the corresponding waveguide energy measured at these two distances for different

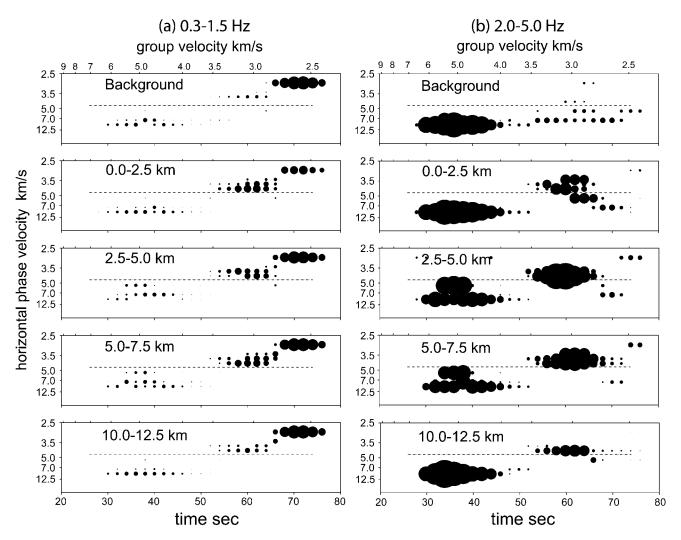


Figure 4. Slowness analysis calculated for the EK model and EK model with random patches at different depths: (a) Frequency band 0.3–1.5 Hz. (b) Frequency band 2.0–5.0 Hz. The top row is for a background velocity model and the lower rows are for models with random patches. The depths of random patches are labeled in the panels. For details, see the text.

frequency bands. The vertical and horizontal coordinates are for measurements at the two distances, and dots represent results for different source depths and velocity models. Although a wide range of near-source structures and source depths are used to generate these measurements, the results show a general linear relationship for all frequency bands. This further verifies that we can use a small model to investigate the near-source energy partitioning robustly.

Investigating Regional Phase Excitation

P-pS-to-Lg and P-to-Lg Conversion

We first investigate the *P-pS*-to-*Lg* conversion caused by near-source lateral velocity variations and assess its effect on the explosion *S*-wave energy budget. In a horizontally layered model with overburden *P*-wave velocity larger than the upper-mantle *S*-wave velocity, the free-surface-reflected *pS* wave has a steep incidence angle and cannot be trapped in the crustal wave guide to form *Lg*. In this case, the energy transfer through *P-pS*-to-*Lg* coupling is almost zero. Although, in general, it is agreed that the existence of near-source lateral velocity variation can increase the *P*-to-*Lg* energy exchange, the detailed mechanism underlying this process is still not fully understood.

Figure 8 compares the simulated *P-pS*-to-*Lg* coupling in models with and without near-surface lateral velocity variations. Figure 8a is for the EK model. A shallow explosion source located at depth 0.5 km generates *P, pS*, and *Rg* waves. Two-dimensional slowness analysis is conducted for selected phases in the wave field and the results are shown together with the wave-field snapshot. The synthetic seismograms were bandpass filtered between 2.0 and 6.0 Hz before the slowness analysis. As seen from the result, the *P*

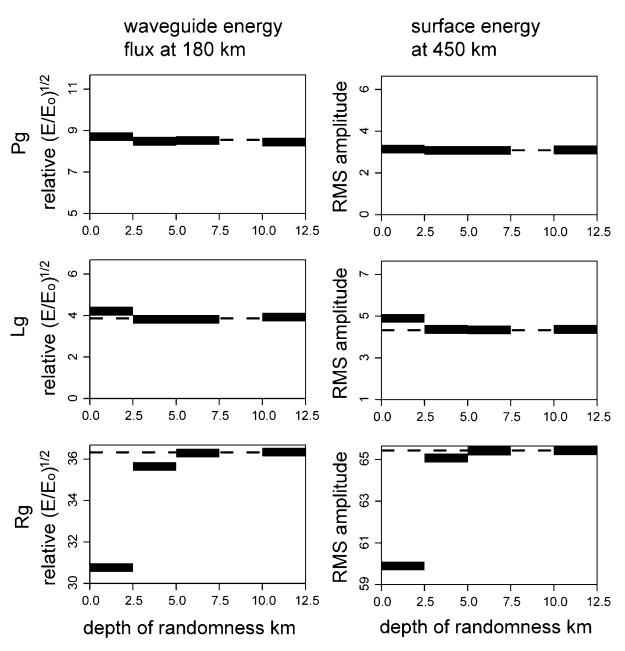


Figure 5. Comparison between wave-guide energy flux at 180 km (left column) and the wave energy on the surface at 450 km (right column) for Pg, Lg and Rg windows. The frequency range is 0.3–1.2 Hz. Shown in each panel is relative energy versus the depth of random patches. Dashed lines indicate the energy level for the background model and short bars indicate the energy changes due to the near-source scattering.

wave leads the wave field and has a distinct slowness. Reverberations within the uppermost crust causes multiply parallel pS wavefronts with their horizontal slowness approximately equal to the overburden P slowness. The pS energy stays to the left of the upper-mantle S slowness and there is no energy transferred from P to Lg. In Figure 8b, a shallow random velocity patch is added to the EK model to test the effect of near-surface scattering. The random patch has a 5% rms velocity fluctuation and is located at distances 5-15 km

and depths 0–2.5 km (shown in the snapshot as a shaded area). The slowness analyses are conducted for P, pS, and pS coda. Although P and early pS waves are barely affected, the pS coda clearly contains some scattered energy with horizontal slowness to the right of the upper-mantle S slowness.

To investigate further the scattering from a shallow random patch, horizontal slowness analysis is conducted at a distance of 20 km and a depth of 0–12.5 km. Figure 9 shows the energy distribution in the slowness–depth domain with

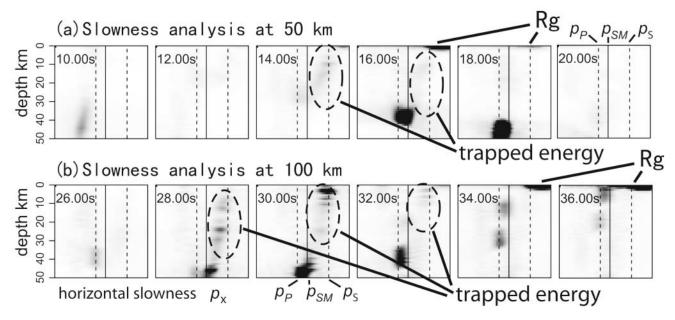


Figure 6. Examples showing the slowness analyses at distances 50 km (a) and 100 km (b). The p_{SM} , p_P , and p_S are upper-mantle S slowness, crustal P slowness, and S slowness, respectively. The energy that can be trapped in the crustal wave guide is indicated in the figure.

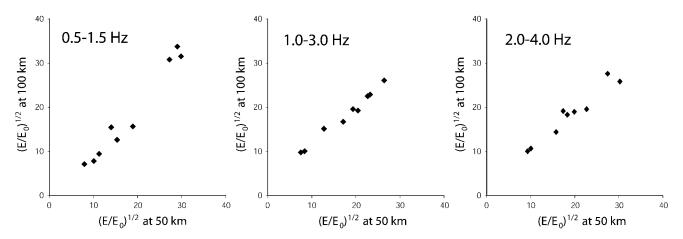


Figure 7. Comparison between trapped wave-guide energy measured at 50 km (horizontal coordinate) and 100 km (vertical coordinate) for frequency bands 0.5–1.5 Hz, 1.0–3.0 Hz, and 2.0–4.0 Hz. Different dots are results from different velocity models and source depths. The results show a general linear relationship for all frequencies.

arrival times and major phases labeled in the frames. The two prominent downgoing phases are the P wave and the free-surface-reflected pS wave. The Rg energy enters the array at 6.0 sec with its depth close to the surface and slowness beyond the S slowness. Figure 9a shows the result using the EK model. Due to the nearly horizontal propagation of the P wave at the free surface, the pS-wave energy has a horizontal slowness that is similar to the overburden P slowness and the energy falls to the left of the upper-mantle S slowness. In Figure 9b and c, shallow random velocity patches with rms velocity fluctuations 3% and 5% are added to the EK model at distances 5–15 km and depths–2.5 km (the same

position as in Fig. 8b). As seen in the figure, scattering causes part of the pS energy to cross the upper mantle S slowness and build up in the dashed rectangles. At shallow depths, the slowness of the scattered energy approaches the S slowness. With an increase in depth, the slowness of this energy gradually merges with the P slowness. The slowness behavior is consistent with scattering of waves at shallow depths, increasing as shallow heterogeneity increases.

Figure 10 investigates scattering taking place at deeper depths. The configuration of the source and model is similar to that used in Figure 8b, except the random patch with 3% rms velocity fluctuation is added to the EK model between

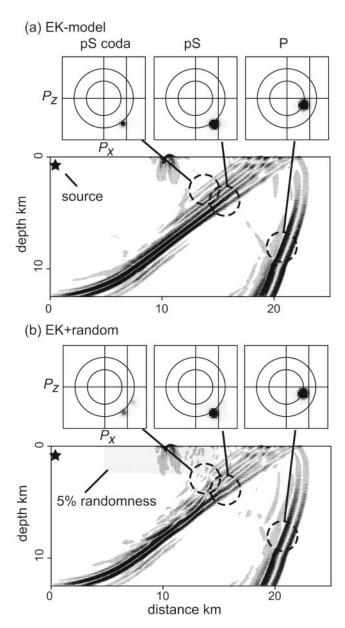


Figure 8. P-pS-to-Lg conversion due to shallow scattering. (a) EK model. (b) EK model with a shallow random patch. The random patch has a 5% rms velocity fluctuation and is shown as a shaded area between horizontal distances of 5 and 15 km and between depths of 0 and 2.5 km. The snapshots and results of slowness analyses of P, pS, and pS coda are shown in the figure. Details are given in the text.

distances 5 and 15 km and depths 2.5 and 10 km (shown in the snapshot as a shaded area). The 2D slowness analysis is conducted for selected phases in the wave field and the results are presented in the figure. After passing through the random region, a P coda is composed of scattered P and S waves generated from the direct P wave. Although the early part of the PS wave does not contribute to the trapped energy, its later part contains energy located to the right of the uppermantle S slowness, which therefore will contribute to the

trapped regional phases. Figure 11 gives the energy distribution in the slowness-depth domain for different models where panel a is for the EK model and panels b and c are for the EK model with 3% and 5% rms fluctuations in a random patch like that used in Figure 10. The slowness analysis is conducted at a distance of 20 km and for depths between 0 and 12.5 km. As expected, with the EK model no energy is seen beyond the upper mantle S slowness, but after the lateral velocity variations are introduced, energy starts to build up to the right of the upper-mantle S slowness. Two types of scattered energy can be found in the slowness-depth domain: weak but widely distributed S energy (indicated by the dashed ellipses) and scattered energy linked to the pSwave (indicated by the dashed rectangles). Both types of energy satisfy the criterion $p_x \ge p_{S-\text{mantle}}$ and will contribute to the L_g wave. The widely spread, scattered S wave is generated by the P-to-Lg coupling through volumetric scattering. The scattering process redistributes the angle spectrum of the original incident waves. Because no lateral heterogeneity exists at the top of the crust, scattered pS waves are generated by the interaction between distorted incident P waves and a smooth free surface.

Comparing Figure 11 with Figure 9, the scattered *pS* wave generated from a deeper random patch appears later than that from a shallow random patch. Both volumetric scattering and scattering near the free-surface affect the general *P*-to-*Lg* conversion.

Contributions from the S*-Wave

For shallow explosion sources, the S^* wave may become a significant contributor to Lg (Gutowski et al., 1984; Lilwall, 1988; Xie and Lay, 1994; Vogfjord, 1997). The amplitude of S* can be large if the source depth is within a fraction of a wavelength from an interface. This makes its excitation highly dependent on the source depth and frequency. Figure 12 shows snapshots for explosion sources at 0.5 km and 3.0 km, respectively. The result clearly shows that a shallow source generates larger S* and Rg waves. We investigate the contribution of the S^* wave within the EK model. Figure 13 shows horizontal slowness analyses at a distance 35 km and for depths between 0 and 30 km. The time window is chosen between 11 to 13 sec after the direct P wave passes the receiver array. The synthetic seismograms are bandpass filtered between 1.0 and 5.0 Hz. The four rows from top to the bottom correspond to source depths 0.25 km, 0.5 km, 1.0 km, and 2.0 km, respectively. The major arrival is the downgoing free-surface-reflected pS wave, which has a horizontal slowness similar to the overburden *P* slowness. As expected for a horizontally layered model, the pS energy stays to the left of the upper-mantle S slowness and has no contribution to the trapped regional phases. For shallow sources, the Rg wave enters the array at about 12 sec and its energy concentrates between 0 and 3 km, as can be seen on the upper-right corners in the slowness-depth domain. For source depth of 2.0 km, the Rg wave is very weak. The S*

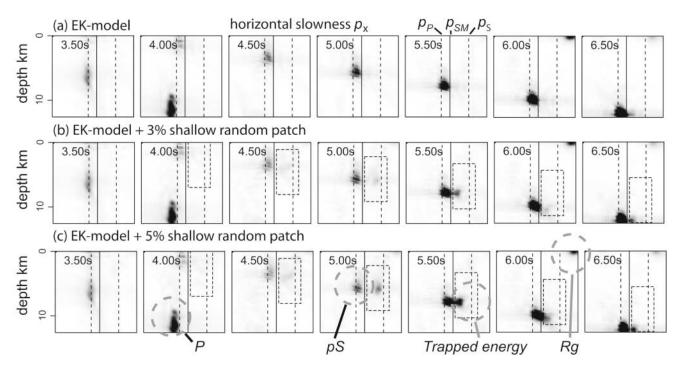


Figure 9. Horizontal slowness analyses for investigating the P-pS-to-Lg coupling with (a) the EK model, (b) the EK model plus a 3% shallow random patch, and (c) the EK model plus a 5% random patch. The p_{SM} , p_P , and p_S are upper-mantle S slowness, crustal P and S slowness, respectively. The slowness analyses are conducted at a distance of 20 km and a depth range of 0–12.5 km. The configuration of the source and model is the same as that used in Figure 8. Major phases are labeled in the figure and energy circled by dashed rectangles is the scattered pS wave.

wave enters the array from a shallow depth and gradually merges with the pS wave (also refer to Fig. 12). The S^* wave is strong for shallow sources and its amplitude decreases with increasing source depth. Very little S^* energy can be observed for source depths below 2 km. In the joint domains, the S^* energy can be isolated and quantified even within a complicated wave field, which is very difficult with remote surface synthetics. The dashed rectangles are the time-slowness-depth window used to locate the S^* energy. The time window is chosen after the arrival of direct P wave, and a variable depth range is chosen to avoid contamination from the Rg wave. The slowness range is chosen between 0.23 and 0.34 sec/km. The energy from successive windows can be summed together to give the contribution of S^* to the trapped regional phases.

The Frequency-Dependent Lg Excitation Function

The frequency dependence of Lg-wave excitation is rooted in the underlying physical processes and is usually controlled by different characteristic scales. For example, the excitation of Lg by S^* , Rg-to-S scattering and spall are all highly source depth dependent. The excitation spectra from individual or joint mechanisms contributing to regional phases depict the frequency dependence of these processes. Frequency-dependent P/S ratios will depend on the excita-

tion functions of multiple phases. We use FDSA to quantify Lg-wave excitation spectra from S^* and pS waves. Figure 14 gives the S*-to-Lg excitation spectra as functions of source depth and frequency. The slowness analysis and multidomain window used to pick the trapped energy are similar to that shown in Figure 13. A series of bandpass filters is used to give responses at different frequencies. The vertical coordinate is the normalized relative energy $(E/E_0)^{1/2}$. Because the source time function has been taken away, the excitation function is the impulse response of the model to the source. The results clearly show that the S^* -to-Lg excitation is generally enhanced for lower frequency and shallow source depth. The major contribution comes from sources located above 1 km. For sources at depths below 1 km, only low-frequency energy below 1 Hz has significant contribution to Lg-wave excitation. However, the responses are also model dependent. For a model with a homogeneous crust (Fig. 14a), the distribution has simple monotonic tendencies in both source depth and frequency. For the EK model (Fig. 14b), the excitation spectrum has a maximum at depth 1 km and a more complicated frequency dependence. This may reflect the fact that the EK model has an interface at 1 km depth. The S* waves generated or reflected from multiple interfaces may interfere with each other and give a complicated frequency spectrum.

To investigate the combined effect for S^* wave and

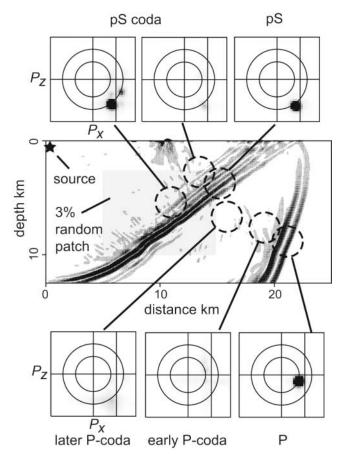


Figure 10. The *P-pS*-to-*Lg* conversion due to a deeper random patch. The random patch has a 3% rms velocity fluctuation and is shown as a shaded region between distances 5 and 15 km and depths 2.5 and 10 km. The slowness analysis for *P*, *P* coda, *pS* and *pS* coda are also shown in the figure.

near-source scattering, we add shallow random-velocity patches to the EK model. The random patch extends between distances of 5 and 25 km and depths of 0 and 2.5 km. Shown in Figure 15a and b are excitation spectra for random patches with rms velocity fluctuations of 3% and 5%, respectively. The most prominent feature is the buildup of high-frequency energy. The scattered energy increases with rms velocity fluctuations. Figure 15c and d isolates the scattered energy by subtracting the excitation spectrum of the EK model from the spectra for models with random velocity patches. Two types of energy can be identified within the frequency-depth domain. The high-frequency energy results from *P-pS*-to-*Lg* and P-to-Lg scattering. This energy is especially important for deeper sources to generate Lg waves, because a deeper source generates little trapped energy in a horizontally layered model. The low-frequency energy concentrated at shallow source depths comes from Rg-to-Lg scattering.

Figure 16 gives the excitation spectra for the EK model with deeper random patches. The random patch is located between distances of 5 and 25 km and depths of 7.5 and 10.0 km. Figure 16a and b gives excitation spectra for random

patches with rms velocity fluctuations of 3% and 5%, respectively. Figure 16c and d gives the isolated scattered energy. The scattered energy from the deeper random patches has little low-frequency content, which supports the interpretation that the low-frequency energy comes from the *Rg*-to-*Lg* scattering. The frequency-dependent excitation spectra establish the relationship between the observations and the characteristics of sources and near-source structures. They provide the basis for evaluating the dominant mechanisms for *Lg*-wave excitation.

Xie (2002) investigated the Pn and Lg spectra from a group of explosions and found that the difference between these spectra requires a nonflat transfer function between the two phases. The Lg-wave excitation function obtained in this article is the impulse response. To compare with the observed Lg spectrum, the source spectrum should be added. Assuming that the Pn spectrum roughly represents the source spectrum, the excitation function obtained here approximates the Pn-to-Lg transfer function. Qualitatively, our excitation function explains the observations of Xie (2002) which require a nonflat Pn-to-Lg transfer function with an enhanced low-frequency excitation for Lg. To make a quantitative comparison, additional investigation is required.

Discussion and Conclusions

A FD modeling plus slowness analysis (FDSA) method has been developed to investigate near-source energy partitioning and Lg-wave excitation of explosive sources. The method has two major advantages. First, it allows us to study the near-source processes in multiple domains, including space, time, slowness, and frequency. This provides an opportunity to isolate different mechanisms within the complex near-source environment. Second, the FDSA method can be applied at a close range, well before the Lg wave is actually formed. It provides us with uncontaminated near-source information by calculating a relatively small velocity model with very fine near-source structures. Because this is a very efficient method, we can use it to investigate a broadfrequency band and to test a large number of source model parameters. As examples, we investigated the contributions of P-pS-to-Lg conversion and S*-to-Lg excitation using models with near-source random velocity fluctuations. The contribution of S*-to-Lg is concentrated at low frequencies and occurs for very shallow source depths. The contribution of P-pS-to-Lg coupling in the presence of near-source smallscale random heterogeneities is concentrated at high frequencies. The excitation spectra of these mechanisms were calculated.

There are other potential Lg excitation mechanisms (e.g., Rg-to-Lg scattering, spall, and tectonic release), which were not systematically investigated in this study. The ability to handle a broad-frequency band makes the FDSA an ideal tool to investigate excitation spectra and P/S-type spectra ratios for different mechanisms and source model parameters. These spectra and spectra ratios form the basis of most

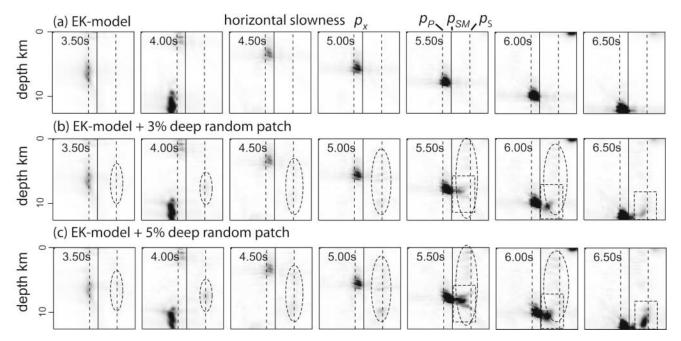


Figure 11. Energy distribution in depth and horizontal slowness domain for (a) the EK model, (b) EK model plus a 3% random patch, and (c) EK model plus a 5% random patch. The configuration of the source and model is same as that used in Figure 10. Energy circled by dashed rectangles is P-pS-to-Lg scattering, and energy circled by dashed ellipses is P-to-Lg scattering.

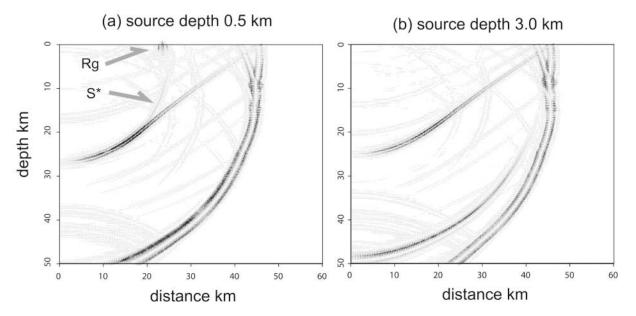


Figure 12. Wave-field snapshots for explosion sources at depths 0.5 km (a) and 3.0 km (b). Note that a shallower explosion is a more efficient source for generating S^* and R_g waves.

regional identification discriminants. Numerical modeling can establish a link between the physical model and observable frequency-dependent features and place regional event identification on a sound physical basis. Scattering from uneven boundary topography should be included in future studies. Although most Lg observations are from vertical-

component seismograms, the tangential component often has as much energy as the vertical component. Because 2D geometry decouples the *P-SV* problem from the *SH* problem, it does not provide any information on the coupling between the source and the *SH* component. The future development of a 3D FDSA method is thus motivated.

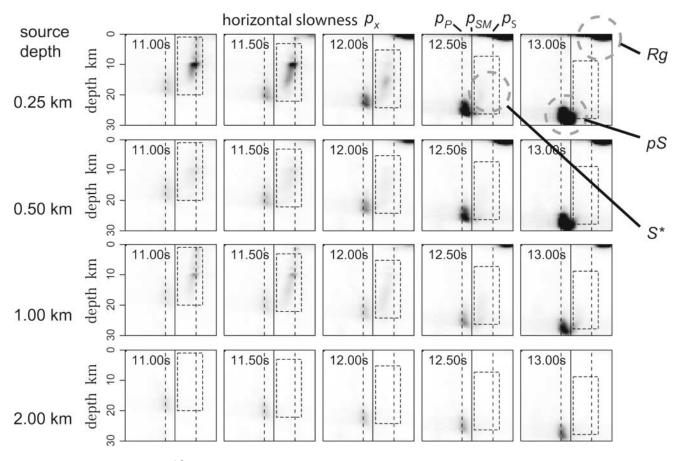


Figure 13. Slowness analysis for investigating S^* -to-Lg conversion. Different rows are for different source depths. Dashed rectangles indicate the time-space-slowness windows used to pick the S^* energy.

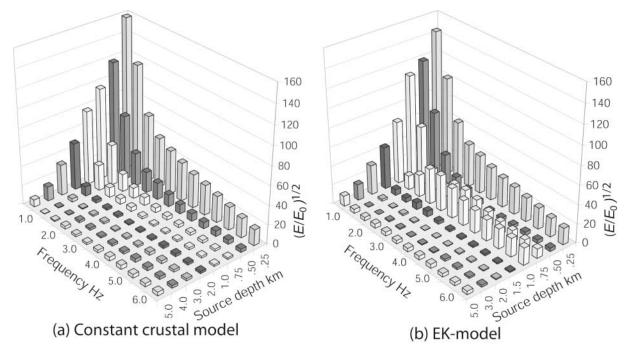


Figure 14. Normalized *Lg*-excitation spectra for sources in different velocity models and at different depths with a model with a homogeneous crust (a) and the EK model (b).

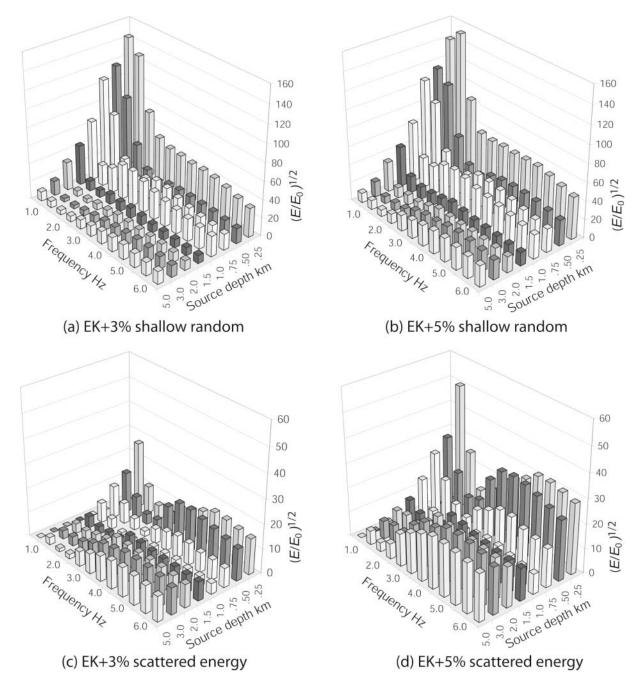


Figure 15. Normalized Lg-excitation spectra for sources in the EK model with shallow random patches, for (a) the EK model with a 3% shallow random patch, (b) the EK model with a 5% shallow random patch, (c) and (d) the isolated scattered energy in (a) and (b), respectively, due to the random patches found by removing the energy for the layered models. Note different vertical scales are used for scattered energy.

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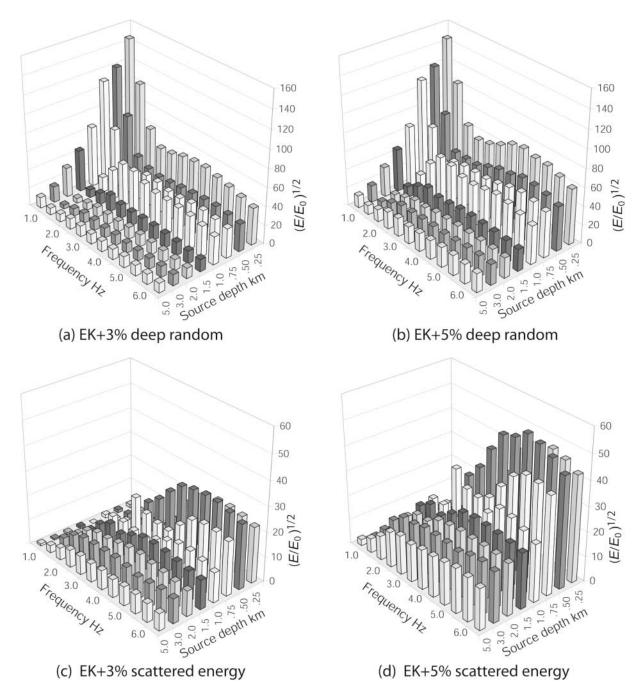


Figure 16. Normalized Lg-excitation spectra for sources in the EK model with deep random patches, for (a) the EK model with a 3% deep random patch, (b) EK model with a 5% deep random patch, and (c) and (d) the isolated scattered energy in (a) and (b) due to the random patches.

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